

# **Ecuaciones Diferenciales Ordinarias**

**Posgrado en ciencias matemáticas UNAM  
IIMAS**

$$\dot{x} = A(t)x + g(x,t), \quad A(t+T) = A(t) \quad \forall t$$

$$g(x, t+T) = g(x, t)$$

$$g(x, \cdot) = O(x^2)$$

### Floquet Theory and linearization around a Periodic orbit.

Suppose that  $\dot{x} = f(x,t), x \in \mathbb{R}^n$

• smooth (at least  $C^1$ )

• Periodic in  $t$ .  $\exists T > 0$  s.t.

$$f(x, t+T) = f(x, t), \quad \forall x \in \mathbb{R}^n, t \in \mathbb{R} \quad (\text{non-autonomous but periodic wr.t. } t)$$

The system can be made autonomous.

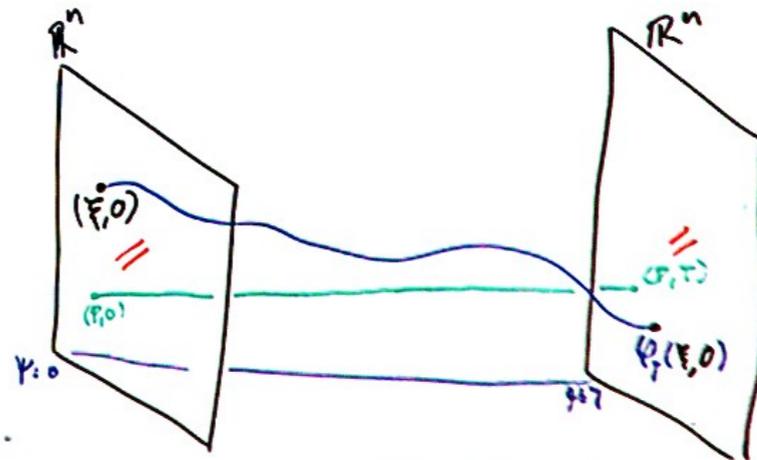
$$\dot{x} = f(x, \psi) \quad (1) \quad \psi \in [0, T] \quad \text{with the endpoints identified,}$$

$$\dot{\psi} = 1 \quad (\text{mod } T)$$

$\psi$  is an angular variable modulus  $T$ .

The phase space is a phase cylinder  $\mathbb{R}^n \times S^1$  (or  $\mathbb{R}^n \times \mathbb{T}$ )

Notice that  $\psi + nT = \psi, \forall n \in \mathbb{Z}$  ← way  
 $\mathbb{T}$  is  $\mathbb{R}$  with points identified in this way  
 $\mathbb{T} = \mathbb{R} \text{ mod } T\mathbb{Z}$   $\psi$  is the flow of (1)



Poincaré map  $\mathcal{P}: \Sigma \rightarrow \Sigma$   
 $\mathcal{P}(\xi) = \psi_T(\xi, 0)$  (in fact this is equal to  $\Pi_x \psi_T(\xi, 0)$  projection.)  
 The set  $\Sigma = \{(\xi, \psi) \mid \psi = 0\}$   
 What happens if  $\exists p \in \mathbb{R}^n, f(p, t) = 0, \forall t \in \mathbb{T}$   
 $\mathcal{P}(p) = p$

$$\dot{x} = A(t)x + g(x,t), \quad A(t+T) = A(t) \quad \forall t$$

$$g(x, t+T) = g(x, t)$$

$$g(x, \cdot) = O(x^2)$$

### Floquet Theory and linearization around a Periodic orbit.

The derivative of  $\mathcal{P}$  w.r.t  $\xi$  is a linear transformation in  $\mathbb{R}^n$  given by  $D_\xi \mathcal{P}(\mathcal{P}) = D_\xi \varphi_T(\mathcal{P}, 0)$

Poincaré: "It is easy to see that  $D_\xi \varphi_t(\mathcal{P}, t)$  is the principal fundamental solution matrix of the problem

The first variation of  $\dot{x} = f(x,t)$

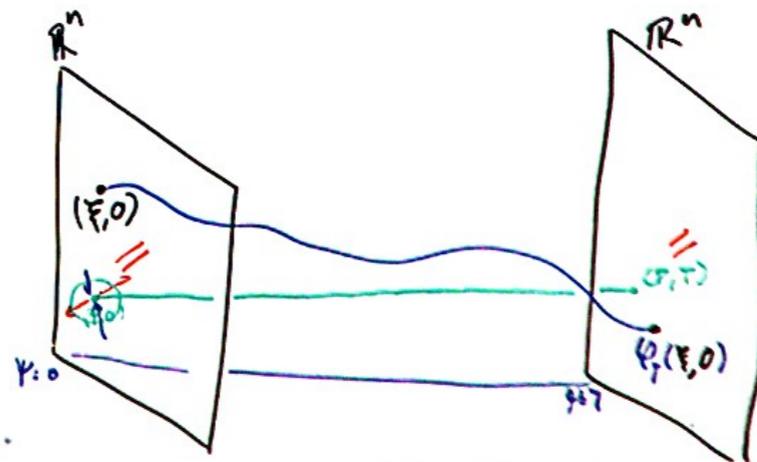
$$\begin{cases} \dot{W} = D_\xi f(\varphi_t(\mathcal{P}, t)) W \\ W(0) = I \end{cases}$$

this is a T-periodic matrix.

Then  $D_\xi \varphi_t(\mathcal{P}, t) = P(t) e^{tB}$   
 if  $t=T$   $D_\xi \varphi_T(\mathcal{P}, 0) = e^{TB}$

The Floquet multipliers coincide with the eigenvalues of the Poincaré map.

Notice that  $\varphi + nT = \varphi, \forall n \in \mathbb{Z}$  ← way  
 $\mathbb{T}$  is  $\mathbb{R}$  with points identified in this way  
 $\mathbb{T} = \mathbb{R} \text{ mod } (\mathbb{Z})$   $\varphi$  is the flow of (1)



Poincaré map  $\mathcal{P}: \Sigma \rightarrow \Sigma$   
 $\mathcal{P}(\xi) = \varphi_T(\xi, 0)$  (in fact this is equal to  $\Pi_x \varphi_T(\xi, 0)$  projection.)  
 The set  $\Sigma = \{(\xi, \eta) \mid \psi = 0\} \simeq \mathbb{R}^n$   
 What happens if  $\exists \mathcal{P} \in \mathbb{R}^n, f(\mathcal{P}, t) = 0, \forall t \in \mathbb{T}$   
 $\mathcal{P}(\mathcal{P}) = \mathcal{P}$

## Lyapunov exponents

(Aleksandr Mikhailovich Lyapunov)

Generalization of Floquet exponents to solutions that are not necessarily periodic.

Let the nonlinear differential equation

$$\dot{x} = f(x), \quad x \in \mathbb{R}^n, \quad f \text{ -smooth} \quad (2)$$

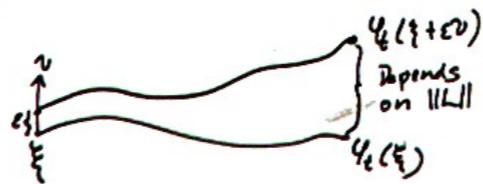
with flow  $\varphi_t$ .

If  $\varepsilon \in \mathbb{R}$ ,  $\xi, v \in \mathbb{R}^n$  and

$$\eta := \xi + \varepsilon v$$

the two solutions start at nearby points.

$$t \mapsto \varphi_t(\xi), \quad t \mapsto \varphi_t(\underbrace{\xi + \varepsilon v}_{\eta})$$



How fast are these two solutions drifting apart?

By Taylor's theorem (around  $\varepsilon=0$ ) we have,

$$\varphi_t(\xi + \varepsilon v) - \varphi_t(\xi) = \varepsilon D_{\xi} \varphi_t(\xi) v + \mathcal{O}(\varepsilon^2)$$

(derivative of  $x \mapsto \varphi_t(x)$ )

Following Poincaré,  $t \mapsto D_{\xi} \varphi_t(\xi)$  is the principal fundamental solution matrix of

$$\dot{W} = Df(\varphi_t(\xi))W, \quad W(0) = \text{Id} \quad (3)$$

**Exercise** Check that if  $\varphi$  is the flow of (2) then  $D_{\xi} \varphi_t(\xi)$  is p.f.s.m. of (3).

We define the linear operator  $L$  for  $v \neq 0, a \in \mathbb{R}$ ,

$$L(av) = D\varphi_t(\xi)av$$

The operator norm measures the "expansion" or "contraction" of a vector,

$$\|L\| = \sup_{a \neq 0} \frac{|D\varphi_t(\xi)av|}{|av|} = \frac{|D\varphi_t(\xi)v|}{|v|}$$

# Lyapunov exponents

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Let the nonlinear differential equation

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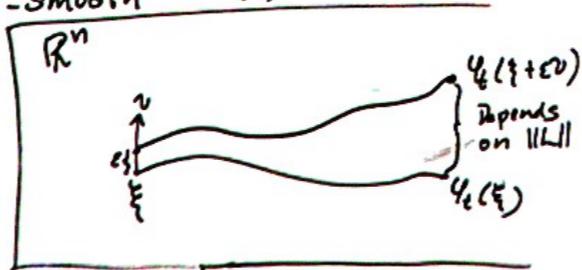
$$\varphi_t(\xi) = \xi + \int_0^t f(\varphi_s(\xi)) ds$$

$$\varphi_t(\xi + \varepsilon v) = \xi + \varepsilon v + \int_0^t f(\varphi_s(\xi + \varepsilon v)) ds$$

$$|\varphi_t(\xi + \varepsilon v) - \varphi_t(\xi)| \leq \varepsilon |v| + \int_0^t |f(\varphi_s(\xi + \varepsilon v)) - f(\varphi_s(\xi))| ds$$

$$\leq \varepsilon |v| + \text{Lip}(f) \int_0^t |\varphi_s(\xi + \varepsilon v) - \varphi_s(\xi)| ds$$

$$|\varphi_t(\xi + \varepsilon v) - \varphi_t(\xi)| \leq \varepsilon |v| \exp(t \cdot \text{Lip}(f))$$



How fast are these two solutions drifting apart?

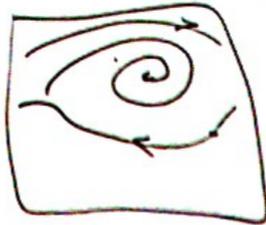
By Taylor's theorem (around  $\varepsilon=0$ ) we have,

$$\varphi_t(\xi + \varepsilon v) - \varphi_t(\xi) = \varepsilon D_\xi \varphi_t(\xi) v + \mathcal{O}(\varepsilon^2)$$

Definition

Let  $\xi \in \mathbb{R}^n$  and a soln to the diff. eq.  $\dot{x} = f(x) \dots (2)$  defined for every  $t \geq 0$ . Also let  $v \in \mathbb{R}^n$  be a non-zero vector. The Lyapunov exponent in the direction of  $v$  for  $\varphi$  is defined by,

$$\lambda(P, v) := \limsup_{t \rightarrow \infty} \frac{1}{t} \log \left( \frac{|D\varphi_t(\xi)v|}{|v|} \right)$$



$$\|L\| = \sup_{\text{ato}} \frac{|D\varphi_t(\xi)v|}{|v|} = \frac{|D\varphi_t(\xi)v|}{|v|}$$

# Lyapunov exponents

(Aleksandr Mikhailovich Lyapunov)

Example

$$\dot{x} = -ax, \quad \dot{y} = by, \quad a, b > 0$$

$$\varphi_t(x, y) = (e^{-at}x, e^{bt}y)$$

$$v = (w, z)$$

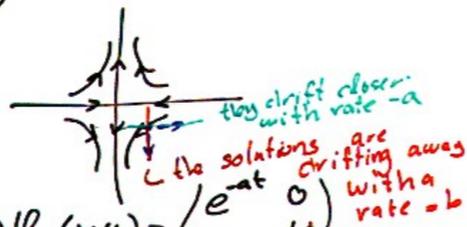
$$w=0, z \neq 0$$

$$\chi(P, v) = \limsup_{t \rightarrow \infty} \frac{1}{t} \log \left( \frac{|(e^{-at} \ 0; 0 \ e^{bt}) \begin{pmatrix} 0 \\ z \end{pmatrix}|}{|z|} \right) = b$$

$$w \neq 0, z=0$$

$$\chi(P, v) = -a$$

Tomorrow we do it for Floquet exponents.



By Taylor's theorem (around  $\varepsilon=0$ ) we have,

$$\varphi_t(\xi + \varepsilon v) - \varphi_t(\xi) = \varepsilon D_\xi \varphi_t(\xi)v + \mathcal{O}(\varepsilon^2)$$

Definition

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