

# **Ecuaciones Diferenciales Ordinarias**

**Posgrado en ciencias matemáticas UNAM  
IIMAS**

# Variedades transversales

$P, Q \subset \mathbb{R}^n$  subvariedades.  $\dim M = n$ ,  $\dim P = k_1$ ,  
 $\dim Q = k_2$ .

$$x \in P \cap Q. \quad f: U \subset \mathbb{R}^n \rightarrow \mathbb{R}^{n-k_1}$$

$$g: V \subset \mathbb{R}^n \rightarrow \mathbb{R}^{n-k_2}$$

$$h: \mathbb{R}^n \rightarrow \mathbb{R}^{n-k_1+n-k_2}$$

$$x \mapsto (f(x), g(x)) \quad T_x P + T_x Q = \mathbb{R}^n$$

$$dh_x = (df_x, dg_x)$$

→ tiene rango máx.

$$k_1 + k_2 \geq n \Rightarrow \underline{n - k_1 + n - k_2} \leq n$$

Por teo. de la dim

$$n = \dim \text{Ker} dh_x + \dim \text{Im} dh_x$$

$$\text{Ker} dh_x = \text{Ker} df_x \cap \text{Ker} dg_x$$

$$T_x P \cap T_x Q$$

$$\dim(T_x P \cap T_x Q) = \dim T_x P + \dim T_x Q - \dim(T_x P + T_x Q)$$

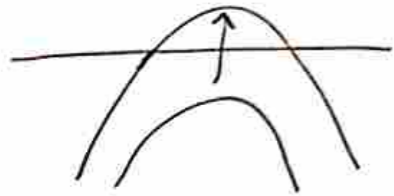
$$\geq k_1 + k_2 - n$$

$$\dim \text{Im} dh_x \leq n + n - k_1 - k_2 = n - k_1 + n - k_2$$

### Normal forms

$$f_{SN}(u, \alpha) = \alpha - u^2$$

$$(\alpha - u^3)$$



Transversal intersection.

$$f_1(u, \alpha) = \underbrace{\alpha_1 + \alpha_2 + \alpha_3}_{\alpha} - u^2$$

### Codimension of a bifurcation

It is the smallest dimension in parameter space that can produce the bifurcation

$$f_{AH}(r, \theta, \alpha) = f(\alpha \pm r^2), 1$$

### Normal form

Is an equation (usually simple) that describes a particular bifurcation and that is top. equivalent to another equation having the same bifurcation.

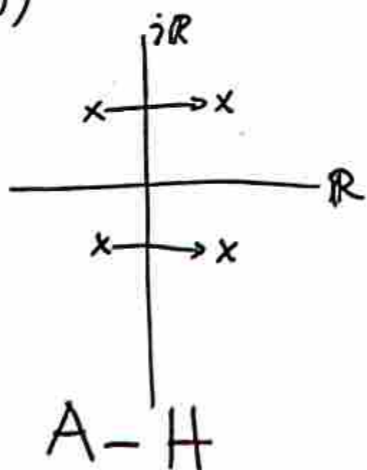
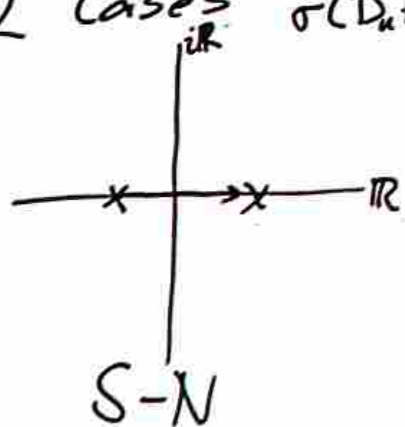
Ex

$\dot{u} = \alpha \pm u^2$  are conjugate to equations that have the S-N bifurcation.

## Normal forms (Saddle-node bifurcation)

A <sup>local</sup> bifurcation can only occur when a fixed point is not hyperbolic.

2 Cases  $\sigma(D_u f(u_0, \alpha))$



Consider

$u = f(u, \alpha)$  and assume that  $f(0,0) = 0$  &  $Df(0,0)$  is not hyperbolic.

Let's prove the following

Lemma [Kuznetsov '98, Lemma 3.1, pg 82]

The system  $\dot{y} = \alpha - y^2 + \psi(y, \alpha) =: F(y, \alpha)$  is topologically equivalent at the origin to

$$\dot{u} = \alpha - u^2$$

where  $\psi(y, \alpha) = O(y^3)$

### Normal forms (Saddle-node bifurcation)

$$\dot{y} = \alpha - y^2 + \psi(y, \alpha) \text{ (1) top. equiv. } \quad \dot{u} = \alpha - u^2 \text{ (2)}$$

Pf

Let's consider the set of fixed points of (1)  
 $\mathcal{M} = \{(y, \alpha) : \alpha - y^2 + \psi(y, \alpha) = F(y, \alpha) = 0\}$

$(0, 0) \in \mathcal{M}$  & notice that  $D_\alpha F(0, 0) = 1$

so by the IFT we can write

$$\mathcal{M} = \{\alpha = g(y)\} \text{ where } g(y) \text{ is smooth}$$

and defined for  $|y|$  small.

Moreover, if we write  $\psi(y, \alpha) = c_1(\alpha)y^3 + c_2(\alpha)y^4 + \text{h.o.t.}$

So when  $\alpha = 0$  we have that

$$g(y) = y^2 + \mathcal{O}(y^3)$$

So for  $|y|$  small, there are two fixed points  $y_1(\alpha), y_2(\alpha)$  that are close to  $\pm\sqrt{\alpha} = X_{\pm}(\alpha)$ .

$$\text{Define } h_\alpha(x) = \begin{cases} x, & \text{if } \alpha \leq 0 \\ a(\alpha) + b(\alpha)x, & \text{if } \alpha > 0 \end{cases}$$

where  $a$  and  $b$  are determined by the condition

$$h_\alpha(x_j(\alpha)) = y_j(\alpha).$$

It is easy to see that  $h_\alpha$  is a homeomorphism and that it conjugates the equations. //

### Normal forms (Saddle-node bifurcation)

•  $\dot{y} = \alpha - y^2 + \psi(y, \alpha)$  top. equiv.  $\dot{u} = \alpha - u^2$  (2)

Now  $\dot{x} = f(x, \alpha)$ ,  $x \in \mathbb{R}$ ,  $\alpha \in \mathbb{R}$ .

$$f(x, \alpha) = c_0(\alpha) + c_1(\alpha)x + c_2(\alpha)x^2 + \mathcal{O}(\alpha^3)$$

We need that  $f$  has a fixed point at  $(0, 0)$   
 $f(0, 0) = 0 \Rightarrow c_0(0) = 0$

Step 1 We use the translation  $\xi = x + \delta$ ,  $\delta(\alpha)$

$$\Rightarrow \dot{\xi} = [c_0(\alpha) - c_1(\alpha)\delta + \mathcal{O}(\delta^2)] + \xi^2 [c_2(\alpha) + \mathcal{O}(\delta)] + \mathcal{O}(\xi^3)$$

Step 2

$$\mu = \mu(\alpha) = c_0'(\alpha)\alpha + \mathcal{O}(\alpha^2) \\ = c_0'(\alpha)\alpha + \alpha^2 \phi(\alpha)$$

And impose that  $\mu'(0) = c_0'(0) = D_x f(0, 0) \neq 0$

$$\dot{\xi} = \mu + a(\mu)\xi^2 + \mathcal{O}(\xi^3), \quad a(\mu) = c_2(0) + \mathcal{O}(\alpha^4)$$

Step 3

Define  $\eta = |a(\mu)|$  and  $\beta = |a(\mu)|\mu$ .

then

$$\dot{\eta} = \beta + (\text{sign}[a(0)])\eta^2 + \mathcal{O}(\eta^3)$$

Thm (Normal form of the saddle-node bifurcation)

$\dot{x} = f(x, \alpha)$ ,  $x \in \mathbb{R}$ ,  $\alpha \in \mathbb{R}$ ,  $f$  smooth.

Suppose that  $f(0, 0) = 0$ ,  $D_x f(0, 0) = 0$

•)  $D_x^2 f(0, 0) \neq 0$ ,  $\therefore D_x f(0, 0) \neq 0$

Then the system is top. equiv. to  $\dot{\eta} = \beta \pm \eta^2$ .



## Normal forms

In general  $\dot{u} = f(u, \alpha)$ ,  $u \in \mathbb{R}^n$

$(0, 0)$  is a fixed point

$D_x f(0, 0)$  is not hyperbolic.

Using center manifold reduction we can transform

$\dot{x} = F(x, \alpha) \rightsquigarrow$  Normal form.

$$\dot{y} = Hy$$

## Lyapunov-Schmidt reduction

Suppose that we are interested in the fixed points of

$$u = f(u, \alpha), \quad u \in \mathbb{R}^n, \quad \alpha \in \mathbb{R}$$

Assume that  $f(0,0) = 0$  and  $D_u f(0,0)$  is not hyperbolic.

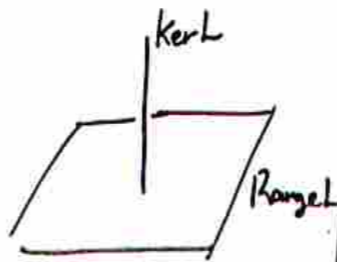
$$f(0,0) = 0, \quad \text{range } D_u f(0,0) = n-1$$

$$L := D_u f(0,0)$$

$$K := \ker L \quad \& \quad R := \text{range } L$$

$$\mathbb{R}^n = K \oplus K^\perp, \quad \dim K = 1$$

$$\mathbb{R}^n = R^\perp \oplus R, \quad \dim R^\perp = 1$$



Let  $P$  be the projection over  $R$ .

$$P^2 = P, \quad \ker P = R^\perp, \quad PL = L$$

We cannot apply the IFT because we have a kernel.

Since  $u \in \mathbb{R}^n = K \oplus K^\perp$ , write

$$u = v + w, \quad v \in K, \quad w \in K^\perp$$

If we want  $f(u, \alpha) = 0$  then

$$Pf(u, \alpha) = 0$$

$$\& (I-P)f(u, \alpha) = 0$$

Define  $F: K \times K^\perp \times \mathbb{R} \rightarrow \mathbb{R}$

$$(v, w, \alpha) \mapsto Pf(v+w, \alpha)$$

$$D_w F(v, w, \alpha)|_0 = D_w Pf(v+w, \alpha)|_0 = PL = L$$

this has range  $n-1$  and we can apply the IFT.

$$\Rightarrow w = w(v, \alpha) \text{ s.t. } Pf(v+w(v, \alpha), \alpha) = 0$$



## Lyapunov-Schmidt reduction

Suppose that we are interested in the fixed points of

$$\dot{u} = f(u, \alpha), \quad u \in \mathbb{R}^n, \quad \alpha \in \mathbb{R}$$

We use  $w(v, \alpha)$  to define

$$\phi: \mathbb{R} \times \mathbb{R} \longrightarrow \mathbb{R}^\perp$$

$$(v, \alpha) \longmapsto (I-P) f(v+w(v, \alpha), \alpha)$$

This is a 1 dimensional problem!

$$\phi(v, \alpha) = (I-P) f(v+w(v, \alpha), \alpha)$$

↳ Bifurcation equation.

For saddle-node

$$\dot{u} = f(u, \alpha), \quad u \in \mathbb{R}^n, \quad \alpha \in \mathbb{R}$$

A fixed point  $u_0$  is a saddle-node at  $\alpha_0$  if  $f(u_0, \alpha_0) = 0$ ,  $D_u f(u_0, \alpha_0)$  has a zero eigenvalue with multiplicity 1.

(SNB1)  $\exists p_0 > 0$  and a curve  $p \mapsto \beta(p) \in \mathbb{R}^n \times \mathbb{R}$

s.t.  $\beta(0) = (u_0, \alpha_0)$  and

$$f(\beta(p)) = 0 \quad \forall |p| < p_0.$$

(SNB2) The function  $\beta$  has a quadratic tangency with  $\mathbb{R}^n \times \{\alpha_0\}$  at  $(u_0, \alpha_0)$  ( $\beta(p) = (\beta_1(p), \beta_2(p))$ ,  $\beta_2(0) = \alpha_0$ ,  $\beta_2'(0) = 0$ ,  $\beta_2''(0) \neq 0$ )

(SNB3)  $p \neq 0$  then  $D_u f(\beta(p))$  is hyperbolic.

We also know that 1 eigenvalue crosses through zero with non-zero velocity.