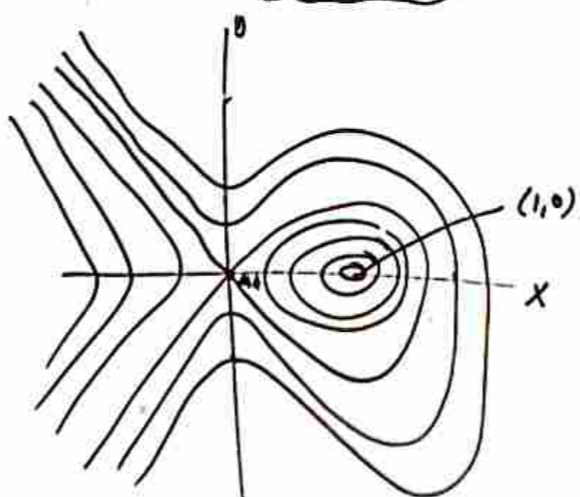
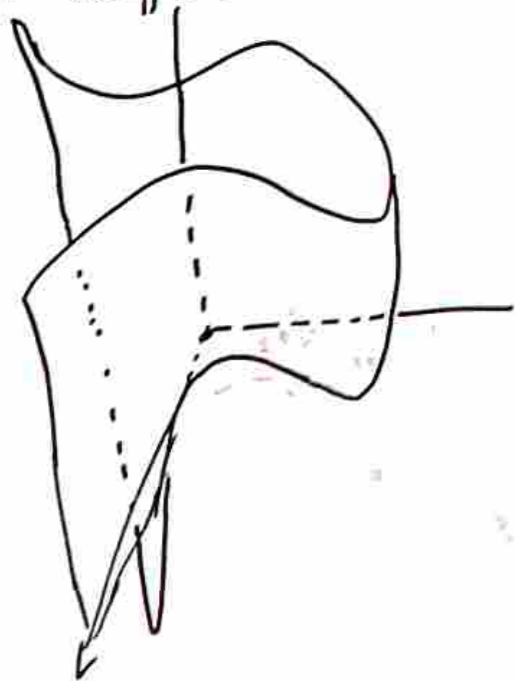


# **Ecuaciones Diferenciales Ordinarias**

**Posgrado en ciencias matemáticas UNAM  
IIMAS**

Grobman - Hartman theorem  
1959 1960

$p$  hyp. fixed point of  $f$   
the flow of  $\dot{x} = f(x)$ ,  $\varphi_t$  restricted to a neighborhood of  $p$   
is conjugate to the flow of the linearized equations  
in a neighborhood of the origin  $\psi(t, y) = e^{tA}y$   
 $A = Df(p)$



Ex (A hamiltonian diff. eq)

$$H: \mathbb{R}^2 \rightarrow \mathbb{R}, H(x, y) = 2x^3 - 3x^2 + y^2$$

$$f(x, y) = \begin{pmatrix} \frac{\partial H}{\partial y}(x, y) \\ -\frac{\partial H}{\partial x}(x, y) \end{pmatrix} = \begin{pmatrix} 2y \\ -6x^2 + 6x \end{pmatrix}$$

$\hookrightarrow$  defines a Hamiltonian v.f.

$$\begin{aligned} \dot{x} &= 2y & \rightarrow \varphi_t \text{ the flow of } \begin{pmatrix} \dot{x} \\ \dot{y} \end{pmatrix} &= f(x, y) \\ \dot{y} &= -6x^2 + 6x & \varphi_t &= (x(t), y(t)) \end{aligned}$$

$$\frac{d}{dt} H(x(t), y(t)) = \frac{d}{dt} (2x(t)^3 - 3x(t)^2 + y(t)^2)$$

$$\begin{aligned} &= 6x(t)^2 \cdot \dot{x}(t) - 6x(t) \cdot \dot{x}(t) + 2y(t) \cdot \dot{y}(t) \\ &= (6x(t)^2 - 6x(t))2y(t) + 2y(t)(-6x(t)^2 + 6x(t)) = 0 \end{aligned}$$

The level curves of  $H$  are invariant.

$$\begin{aligned} 1) y=0, x=0 \quad \begin{matrix} \dot{x}=0 \\ \dot{y}=0 \end{matrix} & Df(x, y) = \begin{pmatrix} 0 & 2 \\ -6x+6 & 0 \end{pmatrix} \text{ at } 1) Df(0,0) = \begin{pmatrix} 0 & 2 \\ 6 & 0 \end{pmatrix}, \lambda = \pm\sqrt{6} \\ 2) y=0, x=1, -6x(x-1)=0 & \text{ at } 2) Df(1,0) = \begin{pmatrix} 0 & 2 \\ 0 & 0 \end{pmatrix} \end{aligned}$$

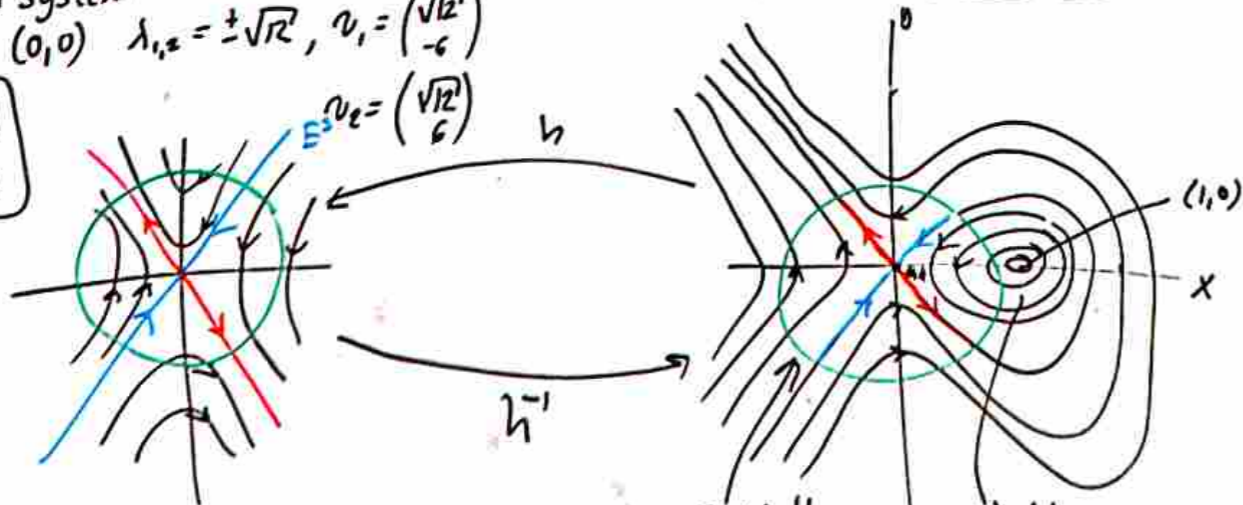
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Linearized system

At  $(0,0)$   $\lambda_{1,2} = \pm\sqrt{6}$ ,  $v_1 = \begin{pmatrix} \sqrt{2} \\ -6 \end{pmatrix}$

$$\begin{cases} \dot{x} = 2y \\ \dot{y} = 6x \end{cases}$$



No but we will talk about the center manifold thm.

Ex (A hamiltonian diff. eq)

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$$f(x,y) = \begin{pmatrix} \frac{\partial H}{\partial y}(x,y) \\ -\frac{\partial H}{\partial x}(x,y) \end{pmatrix} = \begin{pmatrix} 2y \\ -6x^2 + 6x \end{pmatrix}$$

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$$\frac{d}{dt} H(x(t), y(t)) = \frac{d}{dt} (2x(t)^3 - 3x(t)^2 + y(t)^2)$$

$$= 6x(t)^2 \dot{x}(t) - 6x(t) \dot{x}(t) + 2y(t) \dot{y}(t) = (6x(t)^2 - 6x(t))2y(t) + 2y(t)(-6x(t)^2 + 6x(t)) = 0$$

The level curves of  $H$  are invariant.

- 1)  $y=0, x=0$   $\dot{x}=0$   $\dot{y}=0$   $Df(x,y) = \begin{pmatrix} 0 & 2 \\ -6x+6 & 0 \end{pmatrix}$  at 1)  $Df(0,0) = \begin{pmatrix} 0 & 2 \\ 6 & 0 \end{pmatrix}$ ,  $\lambda = \pm\sqrt{6}$
- 2)  $y=0, x=1$ ,  $-6x(x-1)=0$  at 2)  $Df(1,0) = \begin{pmatrix} 0 & 2 \\ -6 & 0 \end{pmatrix}$ ,  $\lambda = \pm\sqrt{6}$

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Example (What if there is decay but no hyperbolicity?)  
(asymptotic stability)

$$f: \mathbb{R}^2 \rightarrow \mathbb{R}^2$$

$$f(x, y) = \begin{pmatrix} -y - x^3 \\ x - y^3 \end{pmatrix}$$

$$\begin{aligned} \dot{x} &= -y - x^3 \\ \dot{y} &= x - y^3 \end{aligned}$$

$(x, y) = (0, 0)$   
is the only fixed point

$$Df(x, y) \Big|_{(0,0)} = \begin{pmatrix} -3x^2 & -1 \\ 1 & -3y^2 \end{pmatrix} \Big|_{(0,0)} = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$$

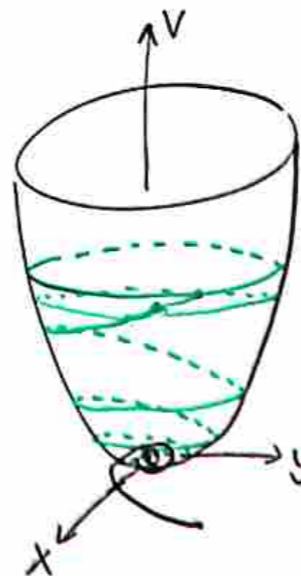
$$\begin{aligned} \lambda^2 + 1 &= 0 \\ \lambda_{1,2} &= \pm i \\ \text{Real part is zero.} \end{aligned}$$

The origin is not a hyperbolic fixed point.  
However, let's notice that we have asymptotic stability.

We consider a function  $V: \mathbb{R}^2 \rightarrow \mathbb{R}$

$$V(x, y) = x^2 + y^2, \quad \varphi_t = (x(t), y(t)) \text{ the flow of } \begin{pmatrix} \dot{x} \\ \dot{y} \end{pmatrix} = f(x, y)$$

$$\begin{aligned} \frac{d}{dt} V(x(t), y(t)) &= 2x(t) \cdot \dot{x}(t) + 2y(t) \cdot \dot{y}(t) \\ &= 2x(t)(-y(t) - x(t)^3) + 2y(t)(x(t) - y(t)^3) \\ &= -2x^4(t) - 2y^4(t) < 0 \end{aligned}$$



This is an example of a Lyapunov function.

has to go downhill  
we descend on the paraboloid.

Then the solution has to go to  
to the origin  $(0, 0)$

Every solution does the same  $\Rightarrow (0, 0)$  is  
asymptotically stable

It's globally asympt. stable.  
This is another central behaviour